Image Classification Networks: classical architectures and common design patterns

Antonia Marcu & Jonathon Hare

Vision, Learning and Control University of Southampton

Motivation: Image Classification

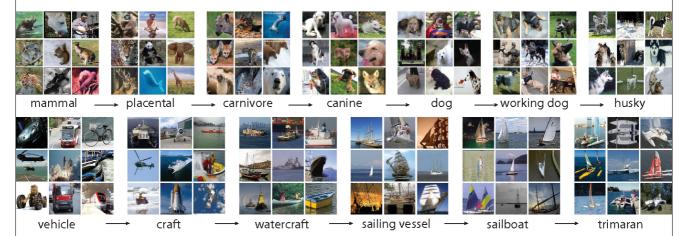
| POOL | POOL | POOL |
|----------------|--------------|--------------------|
| | LU RELU RELU | - a certificated a |
| CONV CONV CONV | CONV CONV CO | NV FC |
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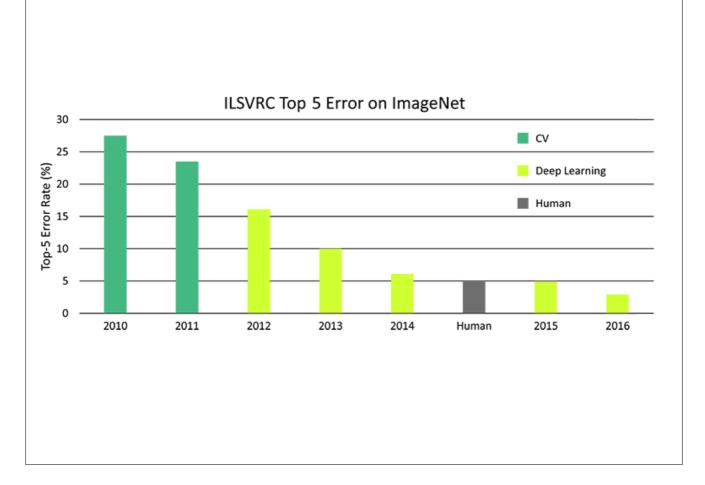
Image Classification Competitions

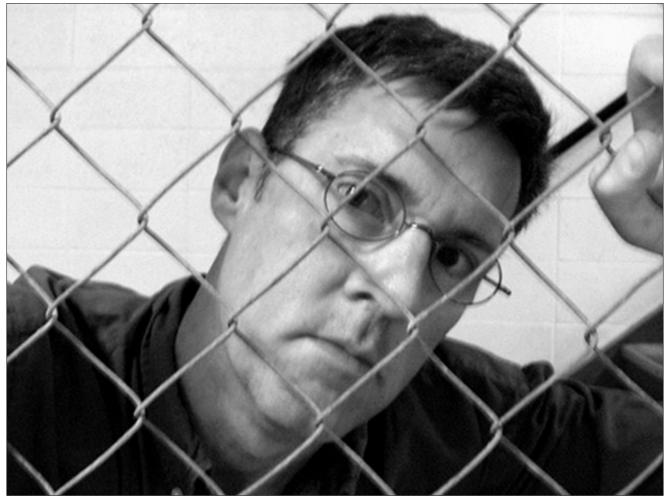
- Corel Dataset, early 2000's
 - Annotation/multi-label classification
 - ~4500/500 small images
- PASCAL VOC Challenges ~2007
 - Object detection and classification

The ImageNet Challenge

- Circa 2009/2010
- ILSVRC Challenge Dataset: 1.3 Million Images in 1000 classes from a larger superset



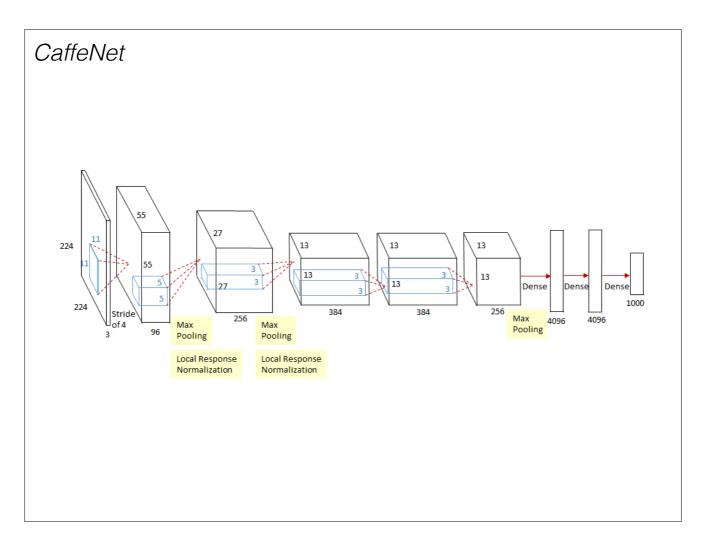


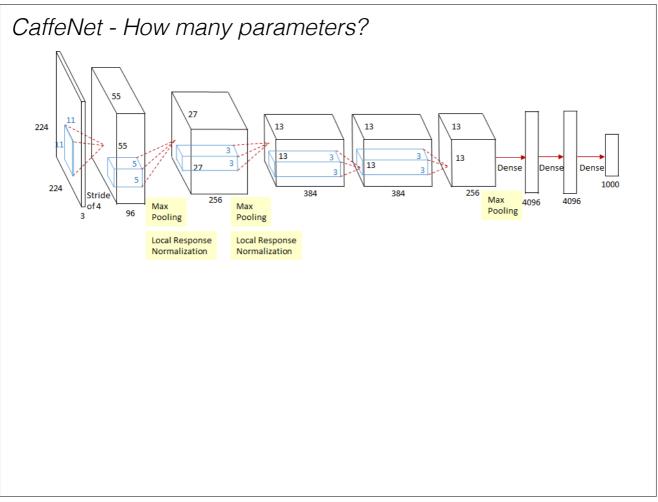


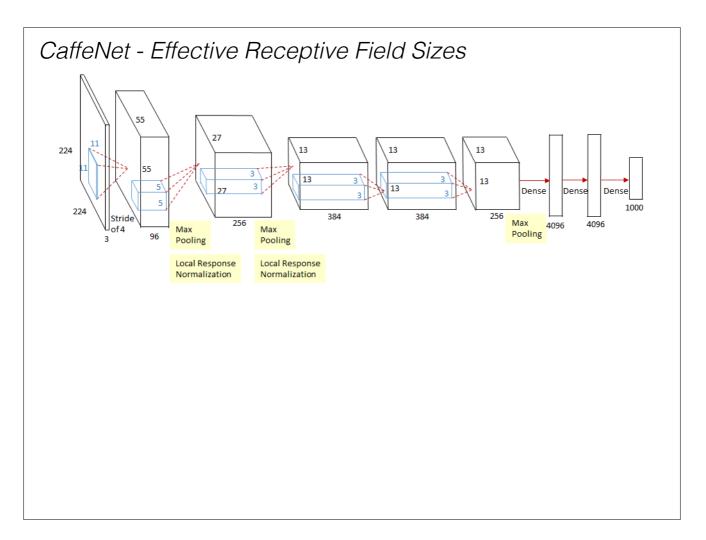
Classic Architectures

AlexNet

ImageNet Classification with Deep Convolutional Neural Networks. <u>https://papers.nips.cc/paper/4824-imagenet-</u> <u>classification-with-deep-convolutional-neural-networks.pdf</u>







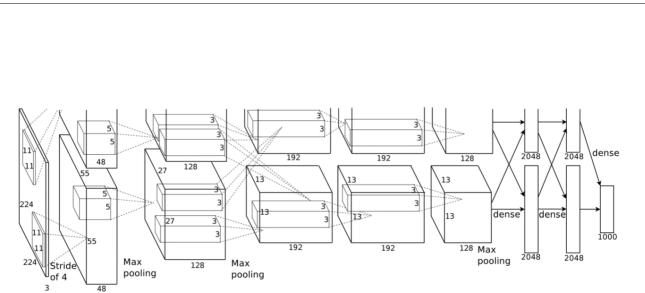


Figure 2: An illustration of the architecture of our CNN, explicitly showing the delineation of responsibilities between the two GPUs. One GPU runs the layer-parts at the top of the figure while the other runs the layer-parts at the bottom. The GPUs communicate only at certain layers. The network's input is 150,528-dimensional, and the number of neurons in the network's remaining layers is given by 253,440–186,624–64,896–64,896–43,264–4096–4096–1000.

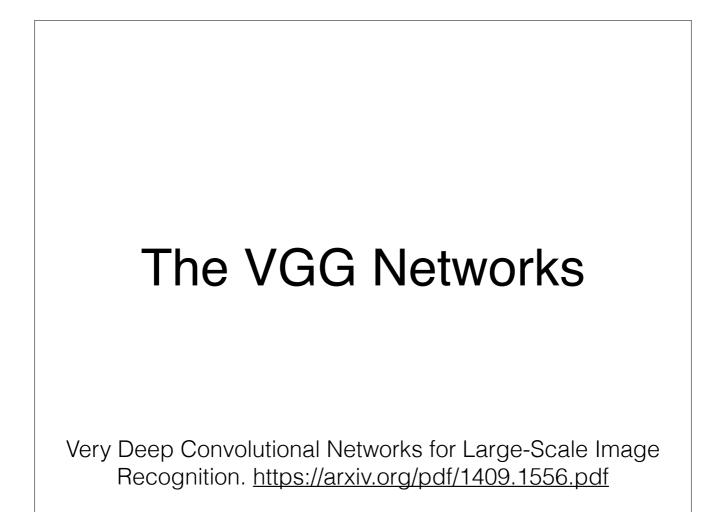
LRN Layers

- The original AlexNet (and the VGG & GoogleLetNet) contained networks "Local Response Normalisation" layers
 - The motivation was to provide locally higher contrast in feature maps

The All CNN

Striving for Simplicity: The All Convolutional Net. https:// arxiv.org/pdf/1412.6806.pdf

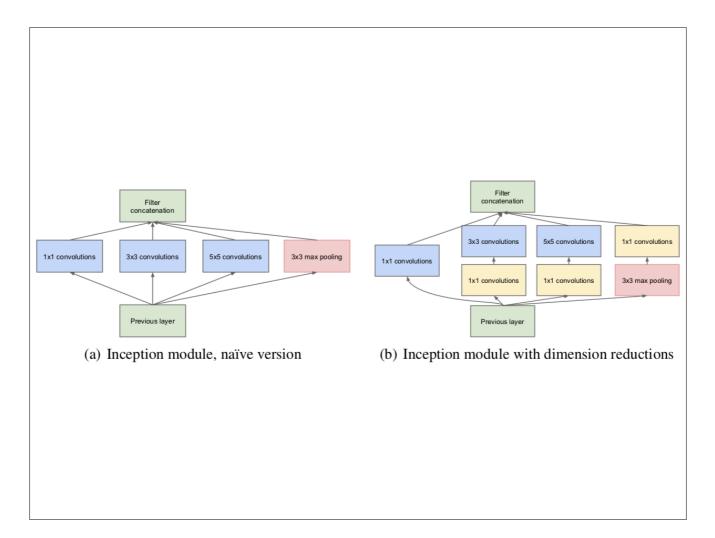
| A | B | С |
|-----------------------------|------------------------------------|-----------------------------|
| | Input 32×32 RGB image | } |
| 5×5 conv. 96 ReLU | 5×5 conv. 96 ReLU | 3×3 conv. 96 ReLU |
| | 1×1 conv. 96 ReLU | 3×3 conv. 96 ReLU |
| | 3×3 max-pooling stride 2 | |
| 5×5 conv. 192 ReLU | 5×5 conv. 192 ReLU | 3×3 conv. 192 ReLU |
| | 1×1 conv. 192 ReLU | 3×3 conv. 192 ReLU |
| | 3×3 max-pooling stride 2 | |
| | 3×3 conv. 192 ReLU | |
| | 1×1 conv. 192 ReLU | |
| | 1×1 conv. 10 ReLU | |
| global ave | raging over 6×6 spatial d | limensions |
| | 10 or 100-way softmax | |
| | - | |

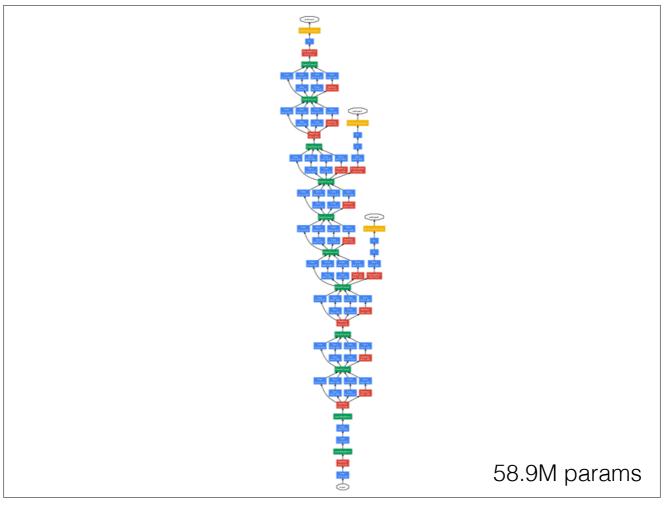


| ConvNet Configuration | | | | | |
|-----------------------|-------------------------------------|-----------|-----------|-----------|-----------|
| А | A-LRN | В | C | D | E |
| 11 weight | 11 weight | 13 weight | 16 weight | 16 weight | 19 weight |
| layers | layers | layers | layers | layers | layers |
| | input (224×224 RGB image) | | | | |
| conv3-64 | conv3-64 | conv3-64 | conv3-64 | conv3-64 | conv3-64 |
| | LRN | conv3-64 | conv3-64 | conv3-64 | conv3-64 |
| | | max | pool | | |
| conv3-128 | conv3-128 | conv3-128 | conv3-128 | conv3-128 | conv3-128 |
| | | conv3-128 | conv3-128 | conv3-128 | conv3-128 |
| | | max | pool | | - |
| conv3-256 | conv3-256 | conv3-256 | conv3-256 | conv3-256 | conv3-256 |
| conv3-256 | conv3-256 | conv3-256 | conv3-256 | conv3-256 | conv3-256 |
| | | | conv1-256 | conv3-256 | conv3-256 |
| | | | | | conv3-256 |
| | | | pool | • | |
| conv3-512 | conv3-512 | conv3-512 | conv3-512 | conv3-512 | conv3-512 |
| conv3-512 | conv3-512 | conv3-512 | conv3-512 | conv3-512 | conv3-512 |
| | | | conv1-512 | conv3-512 | conv3-512 |
| | | | | | conv3-512 |
| | | max | pool | | |
| conv3-512 | conv3-512 | conv3-512 | conv3-512 | conv3-512 | conv3-512 |
| conv3-512 | conv3-512 | conv3-512 | conv3-512 | conv3-512 | conv3-512 |
| | | | conv1-512 | conv3-512 | conv3-512 |
| | | | | | conv3-512 |
| | | | pool | | |
| | | | 4096 | | |
| | | | 4096 | | |
| FC-1000 | | | | | |
| | | | | | |

GoogLeNet and the Inception Module

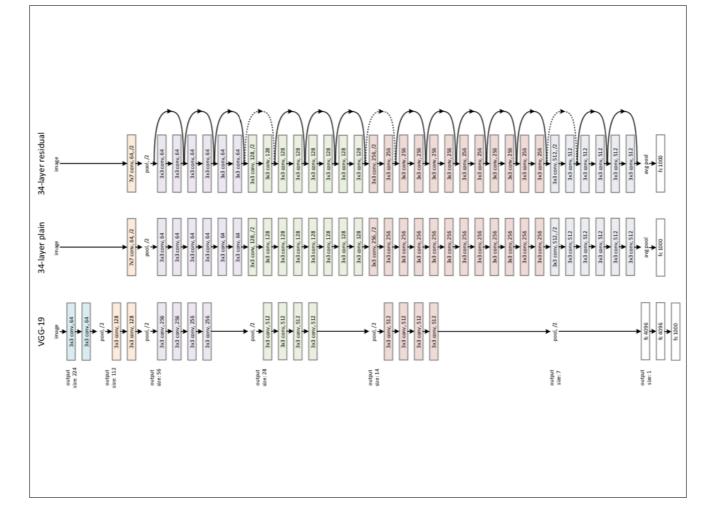
Going Deeper with Convolutions. https://arxiv.org/pdf/ 1409.4842





Deep Residual Networks / ResNet

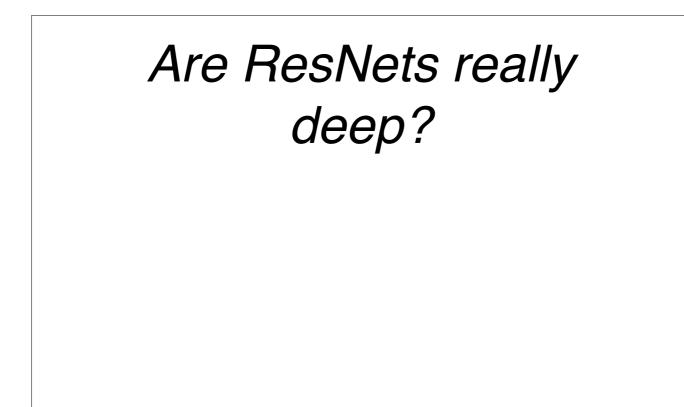
Deep Residual Learning for Image Recognition. <u>https://</u> <u>arxiv.org/pdf/1512.03385.pdf</u>



Do deeper ResNets get you better performance?

| method | | | error (%) |
|------------------|----------|----------|-------------------------|
| Maxo | out [10] | | 9.38 |
| NI | 8.81 | | |
| DSN [24] | | | 8.22 |
| | # layers | # params | |
| FitNet [35] | 19 | 2.5M | 8.39 |
| Highway [42, 43] | 19 | 2.3M | 7.54 (7.72±0.16) |
| Highway [42, 43] | 32 | 1.25M | 8.80 |
| ResNet | 20 | 0.27M | 8.75 |
| ResNet | 32 | 0.46M | 7.51 |
| ResNet | 44 | 0.66M | 7.17 |
| ResNet | 56 | 0.85M | 6.97 |
| ResNet | 110 | 1.7M | 6.43 (6.61±0.16) |
| ResNet | 1202 | 19.4M | 7.93 |

Table 6. Classification error on the **CIFAR-10** test set. All methods are with data augmentation. For ResNet-110, we run it 5 times and show "best (mean \pm std)" as in [43].



Training Classification Networks

Overfitting is a serious concern

- Early nets used dropout extensively
 - BatchNorm has replaced this in more recent architectures
- Significant amounts of data augmentation (the original AlexNet had 2048 augmentations for each training image!)

Competing in ImageNet

- Almost all the winners use a form of test-time augmentation
 - Take multiple views of the input image (e.g. AlexNet took 10 augmentations) and average over the classifications.